

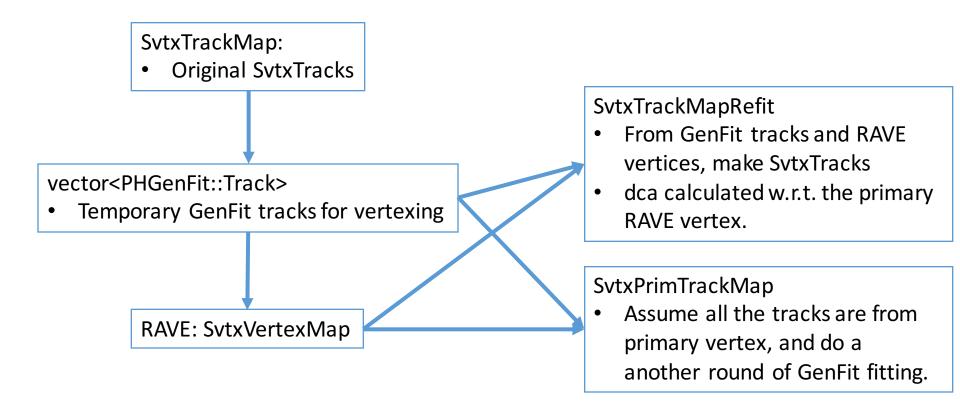


# BJet Tagging: DCA3d

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## Refitting procedure



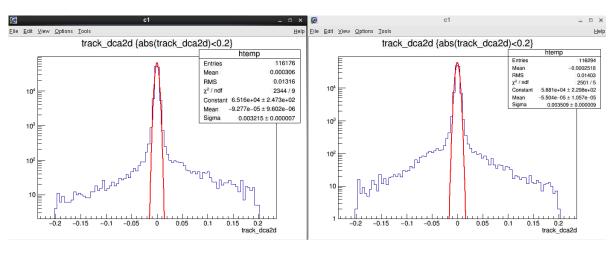
These was done using <a href="PHG4TrackKalmanFitter">PHG4TrackKalmanFitter</a> module in g4hough

# dca2d before and after genfit refit

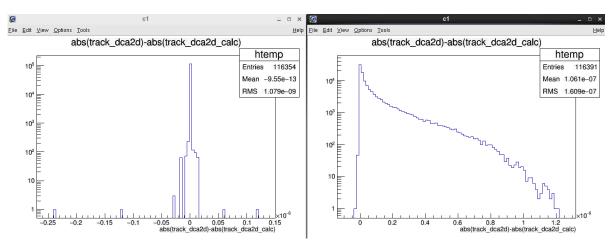
#### Before refit

#### After Refit

dca2d



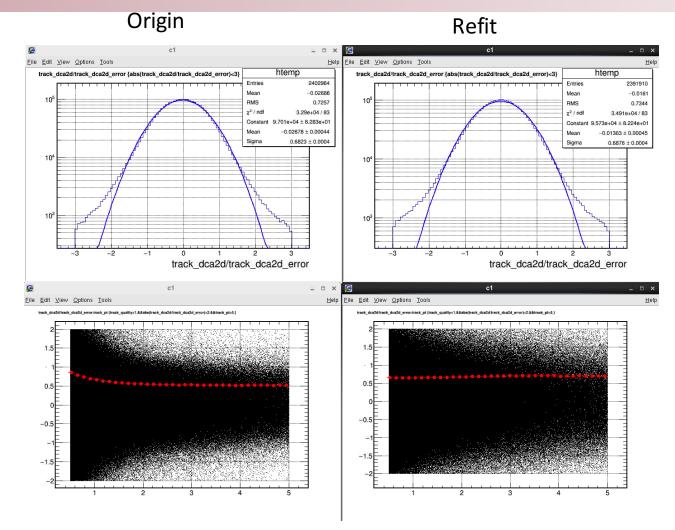
dca2d compared with dca2d from strait line calculation



### dca2d error

track-by-track dca2d/error

dca2d/error vs. pT



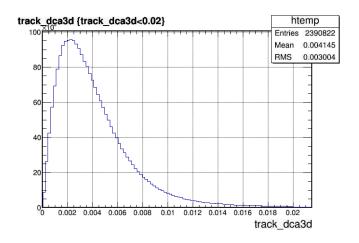
These refit results uses truth vertex(0,0,0) and zero errors for the vertex to isolate the DCA error itself. Same procedure used for the DCA3d plots.

#### dca3d calculation in GenFit

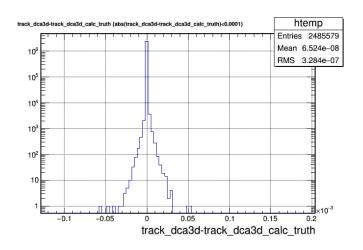
- GenFit can propagate a track to POCA (point of closest approach) of a designated point.
- The states at POCA is defined on a plane that go through the designated point, and perpendicular to the track momentum.
- A GenFit state is (1/p, u', v', u, v).
- dca3d := sqrt(u<sup>2</sup>+v<sup>2</sup>)
- dca3d\_error := sqrt( cov(u,u) + cov(v,v) ) → correlation between u and v ignored.

- n is the mom direction
- u always has one dimension set to be 0. could be x, y or z.
- u, v correlation is 3 4 magnitude smaller than their own error.

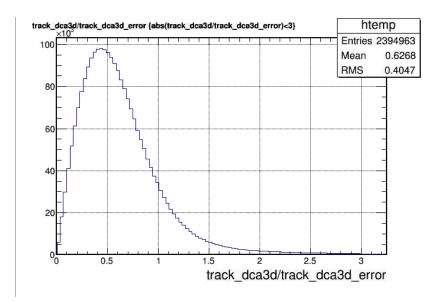
#### dca3d



#### dca3d compared with strait line calculation



#### dca3d/error



# Backups:

10 events: simulation + BJetModule X 2 = 2min

1000 events: 200min